

## Pseudocode for ISR.c

This module responds to the Transmit and Receive ISR resulting from UART

### Data private to the module:

Index

Initiate Packet\_received to false

### Function : void \_\_interrupt() myIsr(void)

Set up SysTickIntHandler (to configure framework timers based on Interrupts from PIC??)

If Receive\_Flag is high and Receive interrupt is high

    Read the byte received

    If index is 2, i.e length byte is received

        Initialize total length variable to save the length from MSB and LSB length

bytes

    Endif

    Inc index

    If index is equal to total length

        Make index 0 again

        Make packet\_received as true

    Endif

If Transmit\_Flag is high and Transmit interrupt is high

    Call Transmit Next() function to initiate the transmit by loading 3<sup>rd</sup> byte into transmit register

Endif

### Function : uint8\_t QueryRegister()

```
{  
    return received byte  
}
```

### Function : bool IsPacketReceived(void)

```
{  
    return packet_received  
}
```

### Function : void ClearReceiveFlag(void)

```
{  
    Return packet_Received false  
}
```